# Ethernet system for the acquisition of dynamic signals 8 SE/diff. inputs, 24-bit, simultaneous acquisition



# MSX-E3601 / MSX-E3601-2

2 or 8 SE/diff. inputs, 24 V

Simultaneous acquisition

2 or 8 current sources for ICP sensors

Onboard calibration

24 V digital trigger input





Operating temperature







Cascadable, can be synchronised









DatabaseConnect

see page 112



More information on www.addi-data.com

# **Features**

- 24 V digital trigger input
- ARM®9 32-bit processor
- 64 MB onboard SDRAM for storing data
- · Robust standardized metal housing
- Power Save Mode: Reduced power consumption when no acquisition runs

#### **Analog inputs**

- 8 SE or diff. inputs, 24-bit, AC/DC coupling
- One A/D converter per channel: simultaneous acquisition on all analog inputs
- Sampling rate up to 128 kHz
- Antialiasing filter
- BNC female connector:
  - inner conductor for positive input
  - outer conductor for negative input (diff) or GND (SE)
- Gain x1, x10, x100

#### **Current sources**

- 8 current sources for the direct connection of ICP™ sensors (integrated circuit piezoelectric)
- 4 mA typ., 24 V max.

#### Safety features

- Status LEDs for fast error diagnostics
- Optical isolation
- Input filters
- Overvoltage protection ± 40 V
- Internal temperature monitoring

### **Interfaces**

- Fast 24 V trigger input
- Ethernet switch with 2 ports
- Synchronisation/trigger In/Out
- Line in for 24 V supply and cascading

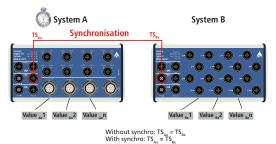
# Communication interfaces

- Web server (configuration and monitoring)
- Command server SOAP for transferring commands
- Data server (TCP/IP or UDP socket) for sending acquisition data
- Event server (TCP/IP socket) for sending system events (Diagnostics such as temperature, short-circuits ...)
- Command server Modbus TCP and Modbus (UDP) for sending commands

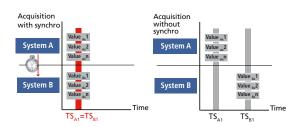
# Synchronisation/time stamp

#### Time stamp

Several MSX-E systems can be synchronised with one another in the  $\mu s$  range through a synchro connection. This allows to start a synchronous data acquisition, to generate trigger events and to synchronise the time on several MSX-E systems. Furthermore, the systems have a time stamp that logs the point in time at which the data was acquired by the system.



The combination of synchronisation and time stamp (TS) allows the clear allocation of signals that were captured by several systems.



MSX-E3601-2



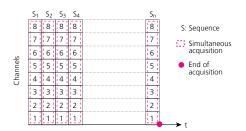


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# **Acquisition modes**

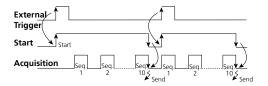
#### Sequence mode

In sequence mode, a list of channels is acquired. Thereby, the single measurement rows are stored one after another. The client receives the acquired values asynchronously to the acquisition through a socket connection. In the sequence mode, the measurement values are read in chronological order, this means the oldest values are read first. The acquisition can be effected continuously, with or without delay or in combination with a hardware or synchro trigger.



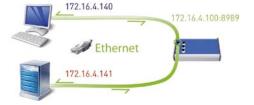
#### Acquisition triggered through trigger or synchro input

**Example:** A measurement process is to be started through an external trigger impulse. For each trigger, 10 sequences are to be acquired. After the acquisition of the 10 sequences they are to be sent to the client.



#### Reading data from a MSX-E system

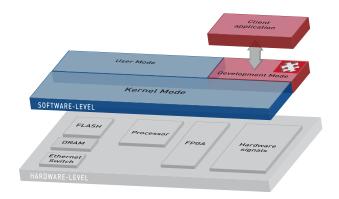
MSX-E systems are multi-client capable, this means several clients (e. g. PC, server, PLC, ...) can read the measurement values of one MSX-E system at the same time. For this, each client establishes a socket connection to the data server of the MSX-E system (port 8989). As soon as the measurement values are available on the data server, the MSX-E system transfers them to the clients.



# Onboard programming / stand-alone operation

#### Development mode

With the Development mode of the MSX-E systems you can customise your measurement, control and regulation applications to fit your requirements. The programs run directly on the MSX-E systems, which has two advantages: external PCs are relieved and you can process data freely according to your requirements. This helps you to improve the efficiency of your processes and to secure your investments.



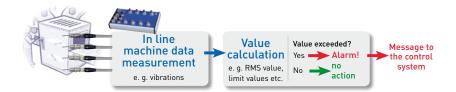
# Anti-aliasing filter

Low-pass filters are used before or during digitising in order to remove all frequency components which are higher than the Nyquist frequency. This is to make sure that the digitised value or result does not contain any unwanted frequencies (aliasing frequencies). According to the Nyquist criterion, in order to obtain the full signal information, the sampling rate must be at least 2 x the signal band width.

#### Firmware and software adaptation

Because MSX-E systems are very flexible, the MSX-E3601 firmware can be easily extended. Thus, calculations such as RMS or limit values etc. can be integrated.

Using the Development Mode, it is possible to create self-sufficient intelligent nodes.



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# ConfigTools

The **ConfigTools** program allows an easy administration of the MSX-E systems. These are automatically detected in the network. **ConfigTools** consists of common and specific functions.

In addition, with **ConfigTools**, the complete configuration of a MSX-E system can be saved and transferred to another system of the same type (clone function).

ConfigTools is included in the delivery.

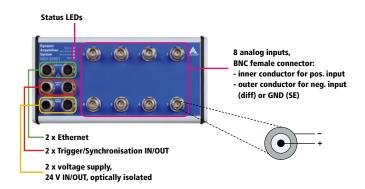
#### ConfigTools functions for MSX-E3601 / MSX-E3601-2:

- Change of IP address
- Display of web interface
- Firmware update
- Save/load system configuration
- Save/load channel configuration

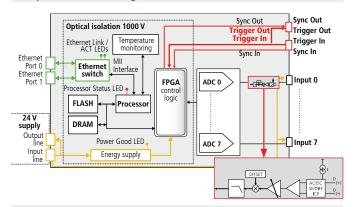
Very easy use through the "ConfigTools" program; The MSX-E system is automatically detected in the network.



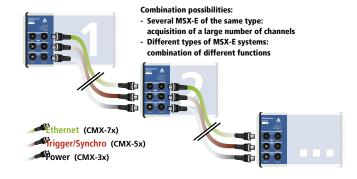
#### **Features**



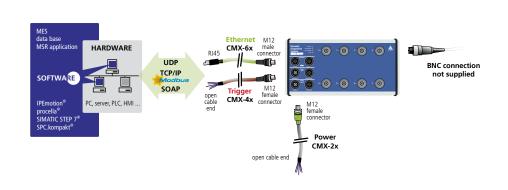
# Simplified block diagram



#### Cascading



# ADDI-DATA connection technology







# **Specifications**

Number of inputs:	8, simultaneous acquisition (MSX-E3601), 1 AD converter				
	per channel 2, simultaneous acquisition (MSX-E3601-2)				
Coupling:	DC, AC (software-configurable)				
Input type:	cingle-ended	or differentia	l (coftware-co	onfigurable)	
Input ranges	single-ended or differential (software-configurable)  SE  Diff				
Gain x1:	± 10 V single	a-ended		differential	
Gain x10:	± 1 V single-ended		± 0.5 V differential		
Gain x100:	± 0.1 V single-ended		± 0.05 V differential		
ADC-Typ:	Oversampled SAR			o v unierentiai	
ADC Typ.	with linear phase FIR antialiasing digital filter				
Resolution:	24-bit				
Sampling rate f <sub>s</sub> :	up to 128 kHz				
Selectable frequencies f <sub>s</sub> :	128000.00	100000.00	80000.00	66666.67	
	64000.00	50000.00	40000.00	33333.33	
	32000.00	25000.00	20000.00	16666.67	
	16000.00	13333.33	12800.00	12500.00	
	10000.00	8000.00	6666.67	6400.00	
	6250.00	5000.00	4000.00	3333.33	
	3200.00	3125.00	2500.00	2000.00	
	1666.67	1600.00	1562.50	1280.00	
- "	1000.00				
Oversampling:	8 x f <sub>s</sub>				
Frequency accuracy:	± 50 ppm				
Input stage characteristics	1.140 // 200				
Input impedance: AC cutoff frequency (-3dB):		pF typ., DC co	oupiea		
Overvoltage protection:	0.48 Hz typ.		/ 1 4 1/ . 100	A	
Overvoitage protection.	Positive input +27 V/-14 V, ± 100mA Max. continuous current				
	Negative input ± 14 V, ± 100mA				
	ivegative inp		continuous cu	rrent	
Filter response		- man			
Passband:	DC up to 0.453 x f, typ.				
Passband ripple:	+/-0.01 dB max. DC up to 0.453 x f <sub>e</sub>				
Bandwidth (-3dB):	0.49 x f <sub>c</sub> typ.				
Stop band:	0.547 x f <sub>c</sub> typ.				
Stop band attenuation:	100 dB min.				
Group delay:	37/f <sub>ς</sub> (μs) typ	L.			
Settling time (latency):		nplete settling	7		
Dynamic characteristics	2 4 7				
Signal-to-noise ration (SNR):	FSR, f <sub>in</sub> =1kH	Z			
- ,	≥ 95 dB	Gain x	ί1		
	≥ 94 dB	Gain x	:10		
	≥ 75 dB	Gain x	100		
Total Harmonic Distortion (THD):	FSR, fin=1kH	lz			
	≥ 100 dB	Gain x	:1		
	≥ 100 dB	Gain x	:10		
		Cain	100		
	$\geq$ 90 dB	Udili X			
Dynamic range:	≥ 90 dB Shorted inpu				
Dynamic range:			:1		
Dynamic range:	Shorted inpu	ts			

Crosstalk:	Ratwaan channals	0-1, 2-3, 4-5, 6-7, with gain x1	
Clossiaik.		hort input, f <sub>in</sub> = 100 Hz	
		hort input, f <sub>in</sub> = 166 Hz	
		0 $\Omega$ input, $f_{in} = 1 \text{ KHz}$	
		0 $\Omega$ input, $f_{in} = 100 \text{ Hz}$	
Phase mismatch:		1-2, 3-4, 5-6, 7-8, with gain x1	
mase mismatch.	± 0.001°	fin < 100 Hz	
	± 0.001 ± 0.01°		
		$f_{in} < 1 \text{ kHz}$	
A !!	± 0.1°	f <sub>in</sub> < 10 kHz	
Amplitude accuracy:	$\pm$ 0.009 dB max. at $f_{in} = 1$ kHz sine signal,		
CLADD	Gain x1, x10, x100		
CMRR:	> 110 dB typ. at DC		
	> 90 dB typ. at f <sub>in</sub> <		
Offset error:	± 90 μV after calibration at 25 °C		
Onboard DC calibration:	Software-configura	able	
Calibration voltage:	5 V typ. Gain x1		
	900 mV typ. Gain x10		
	90 mV typ. Gain x1	100	
Temperature drift:	± 8 ppm/°C typ.		
Sensor supply voltage			
Number of channels:	2 (MSXE-3601-2) or 8 (MSX-E3601)		
	positive input		
Current source:	4 mA typ. to 24 V max.		
Coupling:	AC (positive input)		
	GND (negative inp	ut)	
Recording duration:	TBD max. at 128 kHz sampling rate on 8 channels		
Current sources			

2 or 8 constant current sources for the supply of the Number:

ICP™ sensors, 4 mA typ., 24 V max.

# Voltage supply, Ethernet, Trigger, Synchro

The specifications for the voltage supply, Ethernet, Trigger, Synchronisation and Electromagnetic Compatibility apply to all MSX-E systems. See page 27.

#### EMC – Electromagnetic compatibility

The product complies with the European EMC directive. The tests were carried out by a certified EMC laboratory in accordance with the norm from the EN 61326 series (IEC 61326). The limit values as set out by the European EMC directive for an industrial environment are complied with. The respective EMC test report is available on request.

System features		
Interface:	Ethernet acc. to specification IEEE802.3	
Dimensions:	215 x 110 x 52 mm	
Weight:	860 g	
Degree of protection:	IP 65	
Current consumption at 24 V:	350 mA typ.	
Operating temperature:	-40 °C to +85 °C	
Connectors for sensors		
for analog inputs:	8 x BNC female connector (MSX-E3601)	

2 x BNC female connector (MSX-E3601-2)

# Ordering information

### MSX-E3601 / MSX-E3601-2

Ethernet system for the acquisition of dynamic signals, 2 or 8 SE/diff. inputs, 24-bit, simultaneous acquisition. Incl. technical description, software drivers and ConfigTools.

#### Connection cables

#### Voltage supply

CMX-2x: Shielded cable, M12 5-pin female connector/open end, IP 65

CMX-3x: For cascading, shielded cable, M12 5-pin

female connector/male connector IP 65

#### Trigger/Synchro

CMX-4x: Shielded cable, M12 5-pin female connector/open end, IP 65

CMX-5x: For cascading, shielded cable, M12 5-pin female connector/male connector IP 65

### Ethernet

CMX-6x: CAT5E cable, M12 D-coded male connector/RJ45 connector CMX-7x: For cascading, CAT5E cable, 2 x M12 D-coded male connector

**S7 Modbus TCP Client Library for S7:** Easy use of the Ethernet systems MSX-E with PLCs

MSX-E 5V-Trigger: Level change of the trigger inputs and outputs to 5 V

MX-Clip, MX-Rail (please specify when ordering!),

MX-Screw, PCMX-1x

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